

Technical data sheet

DR24A-MP-7



Communicative rotary actuator for butterfly valves

- Nominal torque <90 Nm
- Nominal voltage AC/DC 24 V
- Control Modulating DC (0)2...10 V Variable
- Position feedback DC 2...10 V
 Variable
- Conversion of sensor signals
- Communication via Belimo MP-Bus



Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
|-----------------|---|--|
| | Nominal voltage frequency | 50/60 Hz |
| | Nominal voltage range | AC 19.228.8 V / DC 21.628.8 V |
| | Power consumption in operation | 9 W |
| | Power consumption in rest position | 2 W |
| | Power consumption for wire sizing | 12 VA |
| | Connection supply / control | Cable 1 m, 4 x 0.75 mm ² |
| | Parallel operation | No |
| Functional data | Torque motor | Max. <90 Nm (not constant) |
| | Positioning signal Y | DC 010 V |
| | Positioning signal Y note | Input impedance 100 kΩ |
| | Control signal Y variable | Open-close |
| | | 3-point (AC only) |
| | Operating range V | Modulating (DC 032 V) |
| | Operating range Y | DC 210 V |
| | Position feedback U Position feedback U note | DC 210 V |
| | | Max. 0.5 mA |
| | Position accuracy | ±5% |
| | Manual override | Gear disengagement with push-button, can be locked |
| | Running time motor | 150 s / 90° |
| | Motor running time variable | 75290 s |
| | Adaption setting range | manual (automatic on first power-up) |
| | Adaption setting range variable | No action |
| | rapion boung range variable | Adaption when switched on |
| | | Adaption after pushing the gear disengagement |
| | | button |
| | Sound power level motor | 45 dB(A) |
| | Position indication | Mechanically (integrated) |
| Safety | Protection class IEC/EN | III Safety extra-low voltage |
| | Protection class UL | UL Class 2 Supply |
| | Degree of protection IEC/EN | IP54 |
| | Degree of protection NEMA/UL | NEMA 2, UL Enclosure Type 2 |
| | EMC | CE according to 2004/108/EC |
| | Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 |
| | Certification UL | cULus according to UL 60730-1A, UL 60730-2- |
| | | 14 and CAN/CSA E60730-1:02 |
| | Mode of operation | Type 1 |
| | Rated impulse voltage supply / control | 0.8 kV |
| | Control pollution degree | 3 |
| | Ambient temperature | -3050°C |
| | Non-operating temperature | -4080°C |
| | Ambient humidity | 95% r.h., non-condensing |
| | Maintenance | Maintenance-free |
| Mechanical data | Connection flange | F07 |
| Weight | Weight approx. | 4.2 kg |



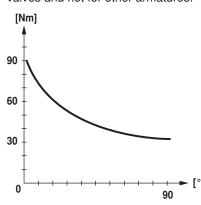
| Safety notes | |
|------------------------------|---|
| | This device has been designed for use in stationary heating, ventilation and air conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport. Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation. The switch for changing the direction of rotation may not be adjusted. The angle of rotation is not permitted to be subjected to mechanical limitation. It is forbidden to alter the mechanical end stops. The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user. Cables must not be removed from the device. The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed. |
| Product features | |
| Principle of operation | Conventional operation: The actuator is connected with a standard modulating signal of DC 010V and drives to the position defined by the positioning signal. The measuring voltage U serves for the electrical display of the actuator position 0100% and as slave control signal for other actuators. Operation on the MP-Bus: The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage. |
| Converter for sensors | Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system. |
| Parameterisable actuators | The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU. |
| Simple direct mounting | Simple direct mounting on the butterfly valve. The mounting orientation in relation to the butterfly valve can be selected in 90° (angle) increments. |
| Manual override | Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked). |
| High functional reliability | The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached. |
| Combination valve/actuator | For valves with the following mechanical specifications in accordance with ISO 5211 F07: - Square stem head SW = 17 mm for form-fit coupling of the rotary actuator. - Hole circle d = 70 mm |
| Home position | The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaption, which is when the operating range and position feedback adjust themselves to the mechanical setting range. The actuator then moves into the position defined by the positioning signal. Factory setting: Y2 (counter-clockwise rotation). |
| Adaption and synchronisation | An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation) |



Product features

Torque not constant Due to

nt Due to the non linear torque characteristic the actuator can only be used for butterfly valves and not for other armatures.



Accessories

| | Description | Туре |
|-----------------------|--|------------|
| Gateways | Gateway MP for BACnet MS/TP, AC/DC 24 V | UK24BAC |
| | Gateway MP to Modbus RTU, AC/DC 24 V | UK24MOD |
| | Gateway MP for LonWorks®, AC/DC 24 V, LonMark-certified | UK24LON |
| | Gateway MP to KNX/EIB, AC/DC 24 V, EIBA certified | UK24EIB |
| | Description | Туре |
| lectrical accessories | Connecting cable 5 m, A+B: RJ12 6/6, To ZTH/ZIP-USB-MP | ZK1-GEN |
| | Connection cable 5 m, A: RJ11 6/4, B: Free wire end, To ZTH/ZIP-USB-MP | ZK2-GEN |
| | Connecting board MP bus suitable for wiring boxes EXT-WR-FPMP | ZFP2-MP |
| | MP-Bus power supply for MP actuators, AC 230/24V for local power supply | ZN230-24MP |
| | Auxiliary switch, add-on, 1 x SPDT | S1A |
| | Auxiliary switch, add-on, 2 x SPDT | S2A |
| | Feedback potentiometer 140 Ohm, add-on | P140A |
| | Feedback potentiometer 200 Ohm, add-on | P200A |
| | Feedback potentiometer 500 Ohm, add-on | P500A |
| | Feedback potentiometer 1 kOhm, add-on | P1000A |
| | Feedback potentiometer 2.8 kOhm, add-on | P2800A |
| | Feedback potentiometer 5 kOhm, add-on | P5000A |
| | Feedback potentiometer 10 kOhm, add-on | P10000A |
| | Description | Туре |
| Service Tools | Service Tool, for MF/MP/Modbus/LonWorks actuators and VAV- Controller | ZTH EU |
| | Belimo PC-Tool, software for adjustments and diagnostics | MFT-P |
| | Adapter to Service-Tool ZTH | MFT-C |
| | ZIP-USB-MP interface | ZIP-USB-MP |

Rotary actuator, communicative, Modulating, AC/DC 24 V, <90 Nm

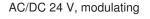


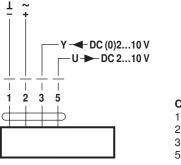
Electrical installation

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- Connection via safety isolating transformer.
 - Direction of rotation switch is covered. Factory setting: Direction of rotation Y2.

Wiring diagrams

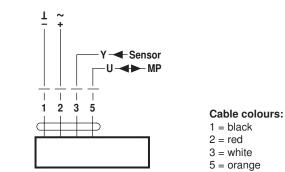






Notes

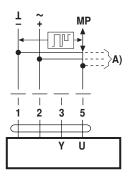
Operation on the MP-Bus



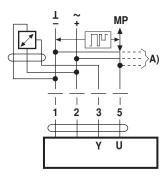
Functions

Functions when operated on MP-Bus

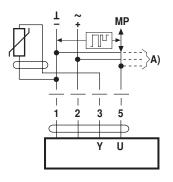
Connection on the MP-Bus



Connection of active sensors



Connection of passive sensors



| A) more | actuators | and | sensors |
|---------|-----------|-----|---------|
| (max.8) | | | |

A) more actuators and sensors

Output signal DC 0...10 V

• Supply AC/DC 24 V

(max. DC 0...32 V)

-28...+98°C

-35...+155°C

850...1600 Ω²⁾

850...1600 Ω²⁾

-10...+160°C¹⁾ 200 Ω...60 kΩ²

Resolution 30 mV

(max.8)

Ni1000

PT1000

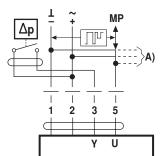
NTC

Network topology

There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable • no shielding or twisting necessary

no terminating resistors required

Connection of external switching contact



A) more actuators and sensors (max.8)

• Switching current 16 mA @ 24 V • Start point of the operating range must be parameterised on the MP actuator as ≥ 0.5 V

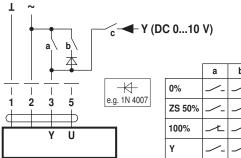
A) more actuators and sensors (max.8)1) Depending on the type2) Resolution 1 Ohm

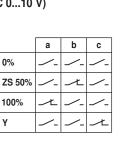


Functions

Functions with basic values (conventional mode)

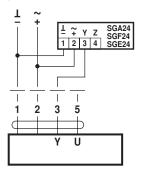
Override control with AC 24 V with relay contacts

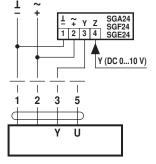




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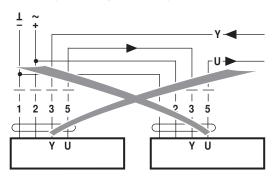
Remote control 0...100% with positioner SG..



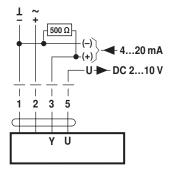


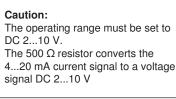
Minimum limit with positioner SG..

Follow-up control (position-dependent)



Control with 4...20 mA via external resistor



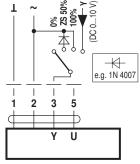


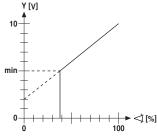


U γ

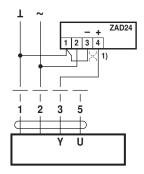
Functional check

Override control with AC 24 V with rotary switch





Position indication



(1) Adapting the direction of rotation

Procedure

1. Connect 24V to connections 1 and 2 2. Disconnect connection 3:

- with direction of rotation Y1: Actuator rotates to the left
- with direction of rotation Y2
- Actuator rotates to the right
- 3. Short-circuit connections 2 and 3:
- Actuator runs in opposite direction

1

1

2

3 5

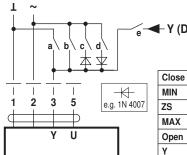
DR24A-MP-7

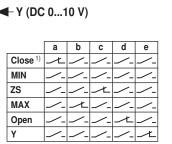


Functions

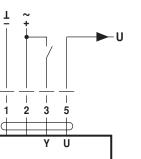
Functions for actuators with specific parameters (Parametrisation with PC-Tool necessary)

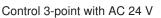
Override control and limiting with AC 24 V with relay contacts

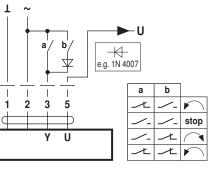




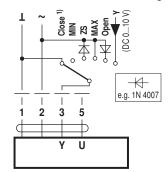
Control open-close





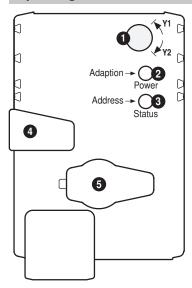


Override control and limiting with AC 24 V with rotary switch



1) Caution: This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

Operating controls and indicators



1 Direction of rotation switch

Switch over: Direction of rotation changes

2 Push-button and LED display green

No power supply or malfunction In operation Press button: Triggers angle of rotation adaptation, followed by standard mode

O Push-button and LED display yellow

| Off: | Standard mode | |
|---------------------------|--|--|
| Flickering: | MP communication active | |
| On: | Adaptation or synchronising process active | |
| Flashing: | Request for addressing from MP master | |
| Press button: | Confirmation of the addressing | |
| Gear disangagement button | | |

Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible Release button: Gear engages, synchronisation starts, followed by standard mode

5 Service plug

Off:

On:

For connecting parameterisation and service tools

Check power supply connection

2 Off and **3** On Possible wiring error in power supply Rotary actuator, communicative, Modulating, AC/DC 24 V, **BELI**

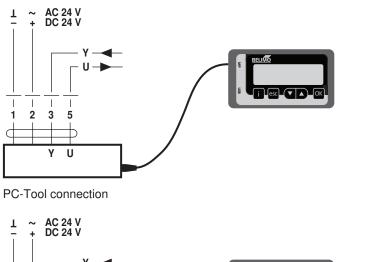


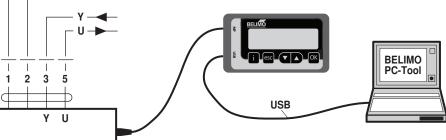
Service



Notes • The actuator can be parameterised by PC-Tool and ZTH EU via the service socket.

ZTH EU connection



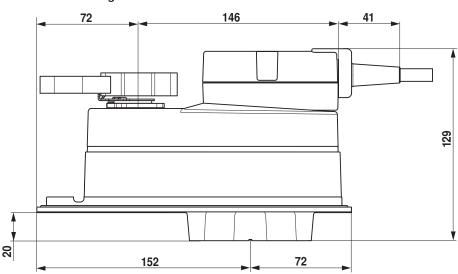


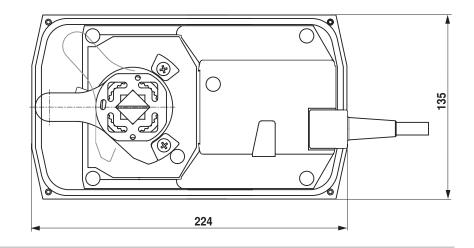
Rotary actuator, communicative, Modulating, AC/DC 24 V, <90 Nm



Dimensions [mm]

Dimensional drawings





Further documentation

- Overview MP Cooperation PartnersTool Connection Guide